

# Organized Information Transmission

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Information is often transmitted in **horizontal** or **vertical** ways.



**Horizontal** transmission refers to informing a group of listeners symmetrically and simultaneously.



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- ▶ Examples: academic seminars, board meetings, press conferences, etc.
- ▶ Transmitting information to many people at once, instead of to each of them individually, minimizes the number of communication channels.



**Vertical** transmission refers to information passed down sequentially, and potentially asymmetrically, from one individual to another.



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- ▶ Examples: hierarchical communication in organizations, viral marketing, etc.
- ▶ Delegating information transmission to the receivers themselves can be cost-saving.



# Contribution

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Focus on two classes of (indirect) information structures as natural “proofs of concept”;

Characterize the outcomes they implement in general finite games;

⇒ Organizational perspective on incomplete information / constrained information design.

Introduce a general taxonomy of information structures which speaks to the horizontal and vertical dimensions of real-world transmission;

Focus on two classes of (indirect) information structures as natural “proofs of concept”;

Characterize the outcomes they implement in general finite games;

⇒ Organizational perspective on incomplete information / constrained information design.

Show their optimality in binary-action environments with complementarities.



In comparison, direct information structures, which invoke the Revelation Principle (Myerson (1991)) and make incentive-compatible action recommendations, do not constrain information horizontally or vertically.

This can make them very difficult to implement in reality.



“The Revelation Principle in mechanism design is both a blessing and a curse [...] It is a curse because direct mechanisms provide such an unrealistic picture of decision-making in organizations.”

Van Zandt (2007)

- ▶ **Information Design**

- ▶ **BAS:** Arieli and Babichenko (2019), Candogan and Drakopoulos (2020), Candogan (2020)
- ▶ **Adversarial selection:** Morris, Oyama and Takahashi (2020), Li, Song and Zhao (2019), Inostroza and Pavan (2020), Mathevet, Perego and Taneva (2020)

- ▶ **Solution Concepts**

Forges (1993, 2006), Bergemann and Morris (2016)

- ▶ **Communication in Organizations**

Radner (1993), Van Zandt (1999), Rantakari (2008), Alonso, Dessein, and Matouschek (2008), Hori (2006), Dessein (2002), Crémer, Garicano, and Prat (2007)

# Preliminaries



- ▶ Set of players:  $\mathcal{J} = \{1, \dots, n\}$ .
- ▶ Uncertain state:  $\omega \in \Omega$  (finite).
- ▶ Prior:  $\mu \in \Delta(\Omega)$ .
- ▶ Payoffs:  $u_i : A \times \Omega \rightarrow \mathbb{R}$ .

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Optimality results : assume

$A_i = \{0, 1\}$  and  $u_i = 0$  if  $a_i = 0$ .

- ▶ Outcome distribution:  $p \in \Delta(A \times \Omega)$ .

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- ▶ An outcome distribution  $p \in BCE(\mu)$  if [Bergemann and Morris 2016]
  1.  $p(A \times \{\omega\}) = \mu(\omega)$  for all  $\omega$
  2.  $\sum_{\omega} \sum_{a_{-i}} p(a, \omega) (u_i(a; \omega) - u_i(a'_i, a_{-i}; \omega)) \geq 0$   
for all  $i, a_i, a'_i$ .

- ▶ Information structure  $(S, P)$ :  $S = \prod_i S_i$  (finite) and  $P = \{P(\cdot|\omega)\}_{\omega \in \Omega}$ .

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- ▶  $p$  is **implemented** by  $(S, P)$  if there is a **(pure strategy) BNE**  $a^*$  s.t.

$$p(a, \omega) = \sum_{s \in S} \mu(\omega) P(\{s : a^*(s) = a\} | \omega) \quad \forall a, \omega.$$

Let  $\mu_i(\cdot|s_i)$  denote  $i$ 's belief about  $(\omega, s_{-i})$ .

- ▶  $i$  is weakly **more informed** than  $j$  at  $s$ , denoted  $i \geq_{\text{Inf}}^s j$ , if

$$\mu_i(\omega, s'_{-i}|s_i, s_j) = \mu_i(\omega, s'_{-i}|s_i)$$

for all  $\omega \in \Omega$  and  $s'_{-i} \in S_{-i}$ .

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for all  $\omega \in \Omega$  and  $s'_{-i} \in S_{-i}$ .

- ▶  $i$  and  $j$  are **equally informed** at  $s$ , denoted  $i =_{\text{Inf}}^s j$ , if  $i \geq_{\text{Inf}}^s j$  and  $j \geq_{\text{Inf}}^s i$ .



# Horizontal vs. Vertical Transmission

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**Horizontal** transmission to  $i$  and  $j$  at  $s$  if  $i =_{\text{Inf}}^s j$ .

**Vertical** transmission from  $i$  to  $j$  at  $s$  if  $i \geq_{\text{Inf}}^s j$  and  $i$  satisfies communication incentives.

**General taxonomy (Organized information structures):** All information structures can be classified according to the extent to which they allow horizontal and vertical transmission.

We will focus on two special classes of organized information structures:

- ▶ single-meeting schemes – illustrating horizontal transmission
- ▶ delegated hierarchies – illustrating vertical transmission

# Characterization:

## Single-Meeting Schemes

In principle (1) the content of a meeting is common knowledge among the participants, (2) who also know the non-participants are less informed.

An information structure  $(S, P)$  is a **single-meeting scheme** if there exist a collection  $\{M(s) \subseteq \mathcal{J} : s \in S \text{ s.t. } P(s) > 0\}$  and at most one  $\tilde{s}_i \in S_i$  for each  $i$  such that:

- (1)  $i \in M(s)$  implies  $i \succsim^s j$  for all  $j \in \mathcal{J}$  and
- (2)  $i \notin M(s)$  implies  $s_i = \tilde{s}_i$ .

# Definition

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- ▶ Information communicated publicly but to a restricted audience:  $i, j \in M(s) \Rightarrow i =_{\text{Inf}}^s j$ .

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- ▶ Non-participation may carry different information for different players:  $\mu_i(\cdot | \tilde{s}_i) \neq \mu_j(\cdot | \tilde{s}_j)$  possible.
- ▶ Many possible meetings ex-ante:  $\{M(s) \subseteq \mathcal{J} : s \text{ s.t. } P(s) > 0\}$  but only one is ever realized.

What strategic outcomes can emerge in a game where incomplete information is described by single-meeting schemes?

Information design: use as constraints in linear programming.

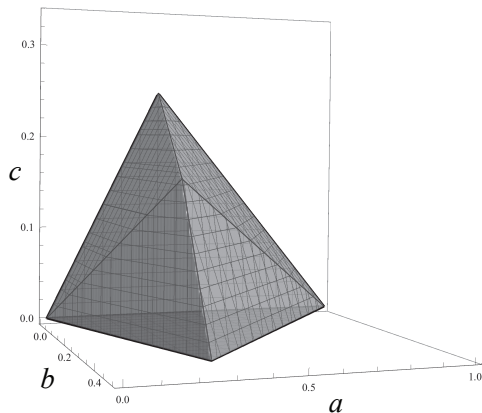


## Theorem 1

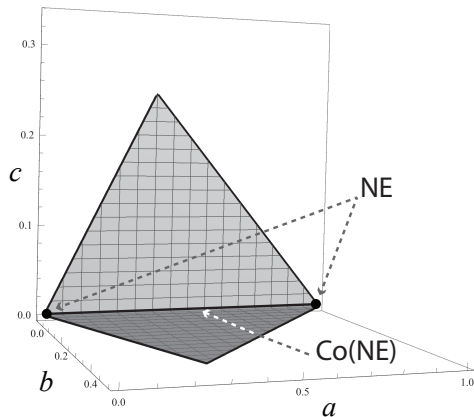
A distribution  $p \in BCE(\mu)$  can be implemented by a single-meeting scheme, if and only if, for all  $i \in \mathcal{J}$ , there is  $\tilde{a}_i \in A_i$  such that for all  $a_i \in A_i \setminus \{\tilde{a}_i\}$

$$\sum_{\omega \in \Omega} p(a_i, a_{-i}, \omega) (u_i(a_i, a_{-i}; \omega) - u_i(a'_i, a_{-i}; \omega)) \geq 0$$

for all  $a'_i \in A_i$  and  $a_{-i} \in A_{-i}$ .



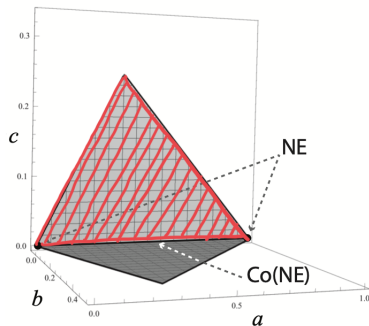
(a) Correlated Equilibria



(b) SMS

	0	1
0	$a$	0
1	$c$	$d$

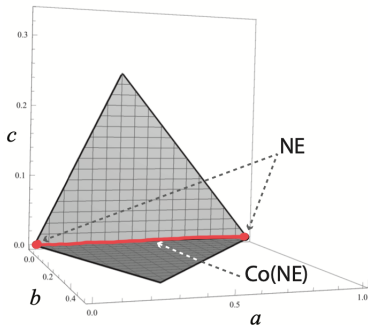
$$\tilde{a}_1 = 1, \tilde{a}_2 = 0$$



(b) SMS

	0	1
0	$a$	0
1	0	$d$

$$\tilde{a}_1 = 0, \tilde{a}_2 = 0 \text{ (or } \tilde{a}_1 = 1, \tilde{a}_2 = 1)$$



(b) SMS

# Characterization:

## Delegated Hierarchies

# Definition

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Two ingredients:

1. To *be able* to vertically transfer information to one another, players must be ordered w.r.t. how informed they are.

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  - ▶ **Information hierarchy:** there exists a total order  $\succeq$  on  $\mathcal{J}$  such that for all  $s$  with  $P(s) > 0$ ,  $i \succeq^s j$  is equivalent to  $i \succeq j$ .

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1. To *be able* to vertically transfer information to one another, players must be ordered w.r.t. how informed they are.
  - ▶ **Information hierarchy:** there exists a total order  $\succeq$  on  $\mathcal{J}$  such that for all  $s$  with  $P(s) > 0$ ,  $i \succeq^s j$  is equivalent to  $i \succeq j$ .
2. To be *willing* to transfer information to one another, truthful communication incentives must be satisfied.



- ▶ Delegated hierarchies allow for direct communication with only the most informed player,  $i^* = \max_{\geq} \mathcal{J}$ .

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- ▶ Sequential cheap talk game beginning with  $i^*$ , in which each player receives information, becomes an informed sender to his immediate successor and chooses an action strategically.
- ▶ In equilibrium: no profitable deviation from truthful information transmission and from equilibrium action.

What strategic outcomes can emerge in a game where incomplete information is described by delegated hierarchies?

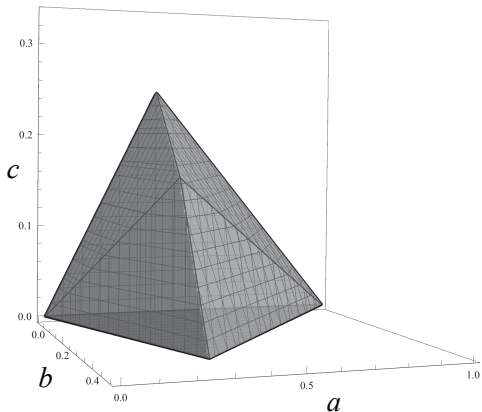
Information design: use as constraints in linear programming.

## Theorem 2

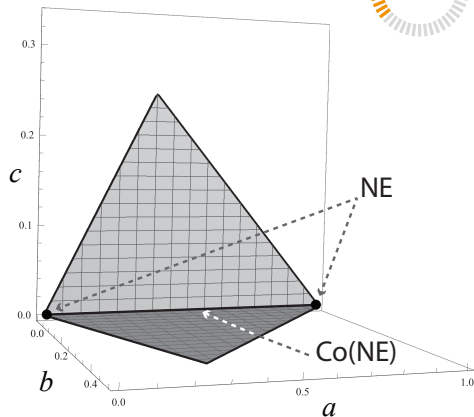
A distribution  $p \in \Delta(A \times \Omega)$  can be implemented by a delegated hierarchy, if and only if,  $p(A \times \{\omega\}) = \mu(\omega)$  for all  $\omega$  and there exists a total order  $\geq$  on  $\mathcal{J}$  such that for all  $a_i, a_{i\leq}$  and  $i \in \mathcal{J}$ ,

$$\sum_{\omega \in \Omega} \sum_{a_{i\leq}} p(a_i, a_{i\leq}, a_{i\geq}, \omega) (u_i(a_i, a_{i\leq}, a_{i\geq}; \omega) - u_i(a'_i, a_{i\leq}, a'_{i\geq}; \omega)) \geq 0$$

for all  $a'_i$  and  $a'_{i\geq}$  such that  $p(a'_{i\geq}) > 0$ .



(a) Correlated Equilibria



(b) SMS & DH

# Optimality

In which optimization problems are single-meeting schemes and delegated hierarchies optimal?



# Optimality of Single-Meeting Schemes

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$v : A \times \Omega \rightarrow \mathbb{R}$  is weakly increasing (in  $A$ ) if

$$a' \geq a \Rightarrow v(a'; \omega) \geq v(a; \omega) \quad \forall \omega \in \Omega.$$

Let  $\mathcal{V}^M = \{v : A \times \Omega \rightarrow \mathbb{R} : v \text{ is weakly increasing}\}$ .

**Assumption 1** (Weak complementarities).

For all  $i \in \mathcal{J}$ ,  $u_i(1, a_{-i}; \omega)$  is weakly increasing in  $a_{-i}$  for all  $\omega \in \Omega$ .

## Proposition 1

If  $\{u_i\}$  satisfy Assumption 1 and  $v \in \text{cone}(\mathcal{V}^M \cup \{u_i\})$ , then there is  $p^* \in \underset{p \in BCE(\mu)}{\text{argmax}} \mathbb{E}_p[v]$  that can be implemented by a single-meeting scheme.

$v : A \times \Omega \rightarrow \mathbb{R}$  is supermodular on  $(A \times \Omega)$  if for all  $a, a' \in A$  and  $\omega' \geq \omega$ ,

$$v(a \vee a'; \omega') + v(a \wedge a'; \omega) \geq v(a; \omega) + v(a'; \omega').$$

Let  $\mathcal{V}^{\text{SM}} =$

$\{v : A \times \Omega \rightarrow \mathbb{R} : v \text{ is supermodular and weakly increasing}\}.$

**Assumption 2** (Supermodularity).

For all  $i \in \mathcal{I}$ ,  $u_i$  is supermodular on  $(A \times \Omega)$ .

## Proposition 2

If  $\{u_i\}$  satisfy Assumption 2 and  $v \in \text{cone}(\mathcal{V}^{\text{SM}} \cup \{u_i\})$ , then there is  $p^* \in \underset{p \in \text{BCE}(\mu)}{\text{argmax}} \mathbb{E}_p[v]$  that can be implemented by a delegated hierarchy.

- ▶ We model the organizational structure of information (with respect to transmission).
- ▶ Focus on two classes of (indirect) information structures:
  - ▶ Characterize the associated strategic outcomes, which are subsets of (Bayes) correlated equilibria.
  - ▶ Show optimality in binary-action environments with complementarities.
- ▶ Extensions: many-(simultaneous) meetings and random delegated hierarchies.



**Thank you!**